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# **mcstas-2.x vs. mcstas-3.0, status and elements of the GPU port**

# McStas 2.x -> McStas 3.0 main differences

- Rewritten / streamlined simplified code-generator with
  - Much less generated code
  - improved compile time and compiler optimizations, esp. for large instrs
  - changes to engine API for component developers
  - definition parameters no longer supported in components (strings, arrays etc. as replacement)
  - much easier to hack/experiment directly on the generated code
  - new USERVARS feature which enriches the particle struct to enable “per particle” flags
  - Much less invasive use of #define
  - Component sections -> functions rather than #define / #undef
  - Much less global variables, instrument, component and neutron reworked to be structures
- Use of #pragma acc ... in lots of places (put in place by cogen where possible)
- New random number generator implemented
- Complete change to dynamic monitor-arrays
- Various tricks relating to GPU

# Main events on timeline of current developments

2017: E. Farhi  
initial cogen  
modernisation

Fall 2018 onwards: J. Garde  
further cogen modernisation and  
restructuring

October 2019 onwards:  
J. Garde & P. Willendrup:  
New RNG, test system, multiple  
functional instruments.

March 2018:  
Participation at  
Dresden Hackathon.  
1st “null” instrument  
prototype runs.

October 2019:  
Participation at Espoo  
Hackathon. First meaningful  
data extracted. Work on  
cogen and realising we need  
another RNG.

November-  
December 2019:  
First good look at  
benchmarks and  
overview of what  
needs doing for first  
release with limited  
GPU support.



NVIDIA mentor: Vishal Metha



NVIDIA mentor: Christian Hundt

# McStas heading for the GPU... March 2018

## McCode on GPU?

1st prototype, “null”-instrument with only one component.

Based on NVIDIA compiler technology, PGCC and OpenACC pragmas



**More to come in 2019!**

McStas / McXtrace instrument

CPU MPI 4 cores (95 % usage)

```

$ time ./run
real 0m0.126s
user 0m0.280s
sys 0m0.028s
$?
16.12 s (Single core 56.0 s)
  
```

16.12 s (Single core 56.0 s)

Port heavy part of component to GPU (Shows some potential)

Port neutron loop to GPU  
Lots of code  
Code generation  
Compiles! Speed up today

GPU 5% usage

```

$ time ./run
real 0m0.431s
user 0m0.356s
sys 0m0.428s
$?
5.43 s
  
```

5.43 s

# McStas heading for the GPU... October 2019

Rewritten code-generation with automated additions of OpenACC pragmas.

Quite transparent wrt. CPU vs. GPU

First simulations with meaningful output

Speed on DELL with Quadro-card ~ on par with running on CPU with MPI

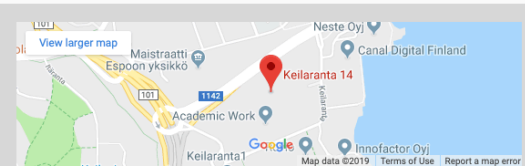
GPU Hackathon

**Introduction**

CSC is in collaboration with Nvidia and the E-CAM European HPC center of Excellence arranging a 3-day GPU hackathon. The GPU hackathon is a coding event in which teams of developers port their applications or kernels to run on GPUs, or optimize their applications that already run on GPUs. In particular the hackathon focuses on applications that can scale up to multiple GPU nodes.

We are looking for teams of 3-4 developers. Collectively the team should know the application intimately. Please keep in mind that we are looking for teams with plans to develop GPU code – not to just run their code on GPUs. During the hackathon each team is supported by one mentor with in-depth GPU programming expertise.

At CSC the new Puhti-AI partition provides 80 nodes with 4 Nvidia Volta GPUs each. This system provides in total more than 2 petaflops of performance. This system is available during the course and accepted teams will also have access to the system beforehand to do some initial porting of the applications to Puhti.



**Date:** 16.10.2019 9:00 - 18.10.2019 17:00

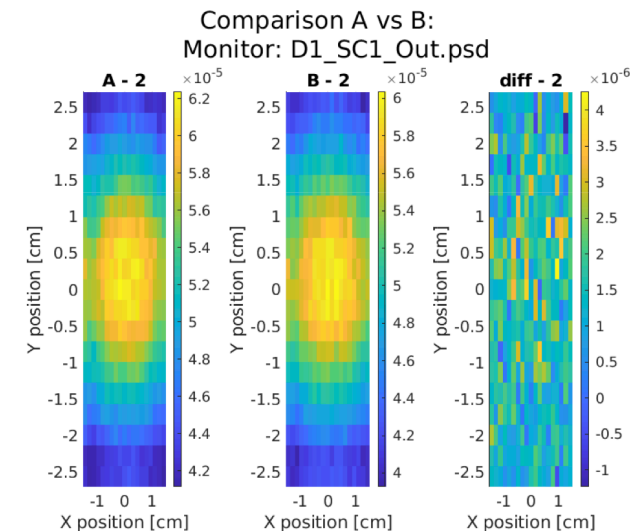
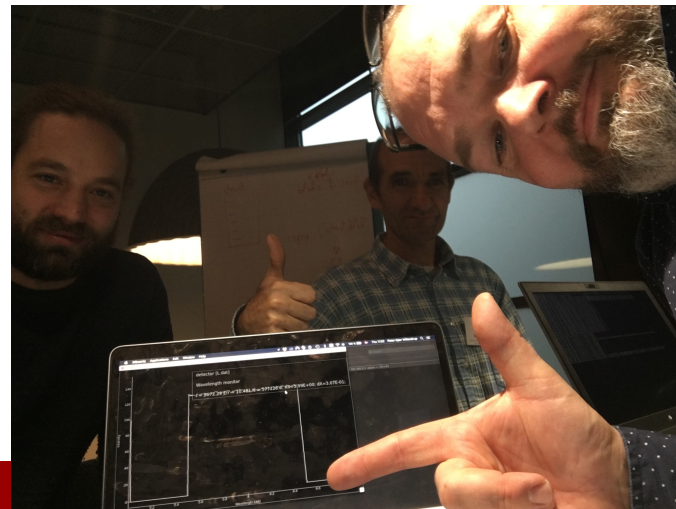
**Location details:** The event is organised at the CSC Training Facilities located in the premises of CSC at Keilaranta 14, Espoo, Finland. The best way to reach us is by public transportation; more detailed [travel tips](#) are available.

**Language:** English

**Price:**

- Free for Finnish universities, universities of applied sciences and governmental research institutes.
- Free for others.

The fee covers all materials, lunches as well as





- Illustration, simple instr with
- Instr vars and “flag”
- Arm
- Source
- Slit
- PSD

example_v25.instr	example_v30.instr
/* * %Example: example.instr dummy=0 Detector: detector_I=345.995 */	/* * %Example: example.instr dummy=0 Detector: detector_I=345.995 */
DEFINE INSTRUMENT Minimal(dummy=0)	DEFINE INSTRUMENT Minimal(dummy=0)
DECLARE %{\n  double constant=2;\n  double two_x_dummy;\n  double flag;\n%}	DECLARE %{\n  double constant;\n  double two_x_dummy;\n%}
INITIALIZE %{\n  two_x_dummy=2*dummy;\n%}	USERVARS %{\n  double flag;\n%}
TRACE	INITIALIZE %{\n  constant=2;\n  two_x_dummy=2*dummy;\n%}
COMPONENT arm = Arm()\nAT (0, 0, 0) ABSOLUTE\nEXTEND %{\n  flag=0;\n%}	TRACE
COMPONENT source = Source_simple(\n  radius = 0.02,\n  dist = 3,\n  focus_xw = 0.01,\n  focus_yh = 0.01,\n  lambda0 = 6.0,\n  dlambd = 0.05,\n  flux = 1e8)\nAT (0, 0, 0) RELATIVE arm	COMPONENT arm = Arm()\nAT (0, 0, 0) ABSOLUTE\nEXTEND %{\n  flag=0;\n%}
COMPONENT coll2 = Slit(\n  radius = 0.01)\nAT (0, 0, 6) RELATIVE arm\nEXTEND %{\n  flag=SCATTERED;\n%}	COMPONENT source = Source_simple(\n  radius = 0.02,\n  dist = 3,\n  focus_xw = 0.01,\n  focus_yh = 0.01,\n  lambda0 = 6.0,\n  dlambd = 0.05,\n  flux = 1e8)\nAT (0, 0, 0) RELATIVE arm
COMPONENT detector = PSD_monitor(\n  nx = 128,\n  ny = 128,\n  filename = "PSD.dat",\n  xmin = -0.1,\n  xmax = 0.1,\n  ymin = -0.1,\n  ymax = 0.1)\nAT (0, 0, 9.01) RELATIVE arm	COMPONENT coll2 = Slit(\n  radius = 0.01)\nAT (0, 0, 6) RELATIVE arm\nEXTEND %{\n  flag=SCATTERED;\n%}
END	COMPONENT detector = PSD_monitor(\n  nx = 128,\n  ny = 128,\n  filename = "PSD.dat",\n  xmin = -0.1,\n  xmax = 0.1,\n  ymin = -0.1,\n  ymax = 0.1)\nAT (0, 0, 9.01) RELATIVE arm
	END

```
example_v30.instr
/*
 * %Example: example.instr
 */
DEFINE INSTRUMENT Minimal(
.
DECLARE %{
X double constant;
double two_x_dummy;
X %}
USERVARS %{
double flag;
%}
INITIALIZE %{
X constant=2;
two_x_dummy=2*dummy;
%}
```

All the stuff usually put in DECLARE earlier like

- double var=3.0;
- function declarations

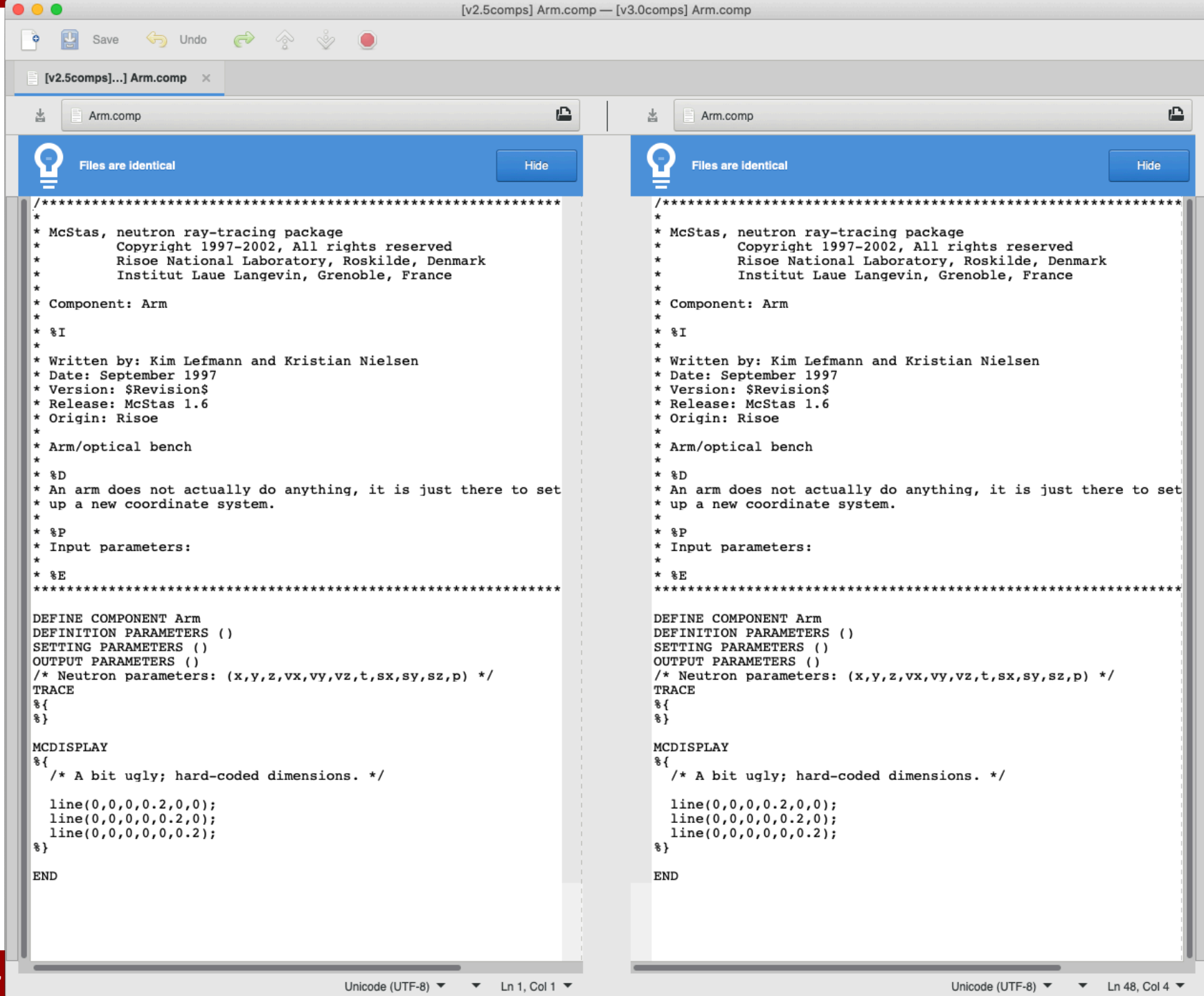
are actually OK to here, but not so in the components.

For symmetry we suggest initialisation in initialise only.

Becomes part of the `_particle` struct, i.e. can change with each particle



# Arm unchanged



The image shows two side-by-side windows of a code editor, each displaying the content of a file named 'Arm.comp'. The top of each window has a blue bar with a lightbulb icon and the text 'Files are identical' and a 'Hide' button. The code in both windows is identical and consists of a header section with asterisks, a component definition section, and a trace section.

```

*****
*
* McStas, neutron ray-tracing package
* Copyright 1997-2002, All rights reserved
* Risoe National Laboratory, Roskilde, Denmark
* Institut Laue Langevin, Grenoble, France
*
* Component: Arm
*
* %I
*
* Written by: Kim Lefmann and Kristian Nielsen
* Date: September 1997
* Version: $Revision$
* Release: McStas 1.6
* Origin: Risoe
*
* Arm/optical bench
*
* %D
* An arm does not actually do anything, it is just there to set
* up a new coordinate system.
*
* %P
* Input parameters:
*
* %E
*****

DEFINE COMPONENT Arm
DEFINITION PARAMETERS ()
SETTING PARAMETERS ()
OUTPUT PARAMETERS ()
/* Neutron parameters: (x,y,z,vx,vy,vz,t,sx,sy,sz,p) */
TRACE
%{
%}

MCDISPLAY
%{
/* A bit ugly; hard-coded dimensions. */

line(0,0,0,0.2,0,0);
line(0,0,0,0,0.2,0);
line(0,0,0,0,0,0.2);
%}

END

```

The left window shows the code at 'Ln 1, Col 1' and the right window shows the code at 'Ln 48, Col 4'. Both windows are set to 'Unicode (UTF-8)' encoding.

# Source\_simple minor changes

```

* Origin: Risoe
*
* A circular neutron source with flat energy spectrum and arbitrary flux
*
* %D
* The routine is a circular neutron source, which aims at a square target
* centered at the beam (in order to improve MC-acceptance rate). The angular
* divergence is then given by the dimensions of the target.
* The neutron energy is uniformly distributed between lambda0-dlambda and
* lambda0+dlambda or between E0-dE and E0+dE.
* The flux unit is specified in n/cm2/s/st/energy unit (meV or Angs).
*
* This component replaces Source_flat, Source_flat_lambda,
* Source_flux and Source_flux_lambda.
*
* Example: Source_simple(radius=0.1, dist=2, focus_xw=.1, focus_yh=.1, E0=14, dE=2)
*
* %P
* radius: [m] Radius of circle in (x,y,0) plane where neutrons
* yheight: [m] Height of rectangle in (x,y,0) plane where neutrons
* xwidth: [m] Width of rectangle in (x,y,0) plane where neutrons
* target_index: [1] relative index of component to focus at, e.g. ne
* dist: [m] Distance to target along z axis.
* focus_xw: [m] Width of target
* focus_yh: [m] Height of target
* E0: [meV] Mean energy of neutrons.
* dE: [meV] Energy half spread of neutrons (flat or gaussian)
* lambda0: [AA] Mean wavelength of neutrons.
* dlambda: [AA] Wavelength half spread of neutrons.
* flux: [1/(s*cm**2*st*energy unit)] flux per energy unit, Angs or meV if flux=0, the
* gauss: [1] Gaussian (1) or Flat (0) energy/wavelength distr.
*
* %E
*****/

DEFINE COMPONENT Source_simple
DEFINITION PARAMETERS ()
SETTING PARAMETERS (radius=0.1, yheight=0, xwidth=0,
dist=0, focus_xw=.045, focus_yh=.12,
E0=0, dE=0, lambda0=0, dlambda=0,
flux=1, gauss=0, int target_index=+1)
OUTPUT PARAMETERS (pmul,square,srcArea)
/* Neutron parameters: (x,y,z,vx,vy,vz,t,sx,sy,sz,p) */
DECLARE
%{
double pmul, srcArea;
int square;
double tx,ty,tz;
%}
INITIALIZE
%{
square = 0;
/* Determine source area */
if (radius && !yheight && !xwidth ) {
square = 0;
srcArea = PI*radius*radius;
} else if(yheight && xwidth) {
square = 1;
srcArea = xwidth * yheight;
}

if (flux) {
pmul=flux*1e4*srcArea/mcget_ncount();
if (dlambda)
pmul *= 2*dlambda:

```

```

* Origin: Risoe
*
* A circular neutron source with flat energy spectrum and arbitrary
*
* %D
* The routine is a circular neutron source, which aims at a square
* centered at the beam (in order to improve MC-acceptance rate). T
* divergence is then given by the dimensions of the target.
* The neutron energy is uniformly distributed between lambda0-dlam
* lambda0+dlambda or between E0-dE and E0+dE.
* The flux unit is specified in n/cm2/s/st/energy unit (meV or Angs)
*
* This component replaces Source_flat, Source_flat_lambda,
* Source_flux and Source_flux_lambda.
*
* Example: Source_simple(radius=0.1, dist=2, focus_xw=.1, focus_yh=
*
* %P
* radius: [m] Radius of circle in (x,y,0) p
* yheight: [m] Height of rectangle in (x,y,0
* xwidth: [m] Width of rectangle in (x,y,0)
* target_index: [1] relative index of component t
* dist: [m] Distance to target along z ax
* focus_xw: [m] Width of target
* focus_yh: [m] Height of target
* E0: [meV] Mean energy of neutrons.
* dE: [meV] Energy half spread of neutrons
* lambda0: [AA] Mean wavelength of neutrons.
* dlambda: [AA] Wavelength half spread of neu
* flux: [1/(s*cm**2*st*energy unit)] flux per energy unit, Angs or
* gauss: [1] Gaussian (1) or Flat (0) ene
*
* %E
*****/

DEFINE COMPONENT Source_simple
DEFINITION PARAMETERS ()
SETTING PARAMETERS (radius=0.1, yheight=0, xwidth=0,
dist=0, focus_xw=.045, focus_yh=.12,
E0=0, dE=0, lambda0=0, dlambda=0,
flux=1, gauss=0, int target_index=+1)
OUTPUT PARAMETERS (pmul,square,srcArea,tx,ty,tz)
/* Neutron parameters: (x,y,z,vx,vy,vz,t,sx,sy,sz,p) */
DECLARE
%{
double pmul;
double srcArea;
int square;
double tx;
double ty;
double tz;
%}
INITIALIZE
%{
square = 0;
/* Determine source area */
if (radius && !yheight && !xwidth ) {
square = 0;
srcArea = PI*radius*radius;
} else if(yheight && xwidth) {
square = 1;
srcArea = xwidth * yheight;
}

if (flux) {

```

# Slit unchanged

```

[v2.5comps] Slit.comp — [v3.0comps] Slit.comp
Save Undo
[v2.5comps...s] Slit.comp
Slit.comp
Files are identical
Hide

/*****
 * McStas, neutron ray-tracing package
 * Copyright 1997-2002, All rights reserved
 * Risoe National Laboratory, Roskilde, Denmark
 * Institut Laue Langevin, Grenoble, France
 *
 * Component: Slit
 *
 * %I
 * Written by: Kim Lefmann and Henrik M. Roennow
 * Date: June 16, 1997
 * Origin: Risoe
 *
 * Rectangular/circular slit
 *
 * %D
 * A simple rectangular or circular slit. You may either
 * specify the radius (circular shape), or the rectangular bounds.
 * No transmission around the slit is allowed.
 *
 * Example: Slit(xmin=-0.01, xmax=0.01, ymin=-0.01, ymax=0.01)
 *          Slit(xwidth=0.02, yheight=0.02)
 *          Slit(radius=0.01)
 *
 * The Slit will issue a warning if run as "closed"
 *
 * %P
 * INPUT PARAMETERS
 *
 * radius: [m]   Radius of slit in the z=0 plane, centered at Origo
 * xmin: [m]     Lower x bound
 * xmax: [m]     Upper x bound
 * ymin: [m]     Lower y bound
 * ymax: [m]     Upper y bound
 * xwidth: [m]   Width of slit. Overrides xmin,xmax if they are unset.
 * yheight: [m]  Height of slit. Overrides ymin,ymax if they are unset.
 *
 *
 * %E
 *****/

DEFINE COMPONENT Slit
DEFINITION PARAMETERS ( )
  SETTING PARAMETERS (xmin=0, xmax=0, ymin=0, ymax=0, radius=0, xwidth=0, yheight=0)
OUTPUT PARAMETERS ( )
/* Neutron parameters: (x,y,z,vx,vy,vz,t,sx,sy,sz,p) */
INITIALIZE
%{
if (xwidth > 0) {
  if (!xmin && !xmax) {
    xmax=xwidth/2; xmin=-xmax;
  } else {
    fprintf(stderr,"Slit: %s: Error: please specify EITHER xmin & xmax or xwidth\n", NAME_CURRENT_COMP); exit(-1);
  }
}
if (yheight > 0) {
  if (!ymin && !ymax) {
    ymax=yheight/2; ymin=-ymax;
  } else {
    fprintf(stderr,"Slit: %s: Error: please specify EITHER ymin & ymax or ywidth\n", NAME_CURRENT_COMP); exit(-1);
  }
}
if (xmin == 0 && xmax == 0 && ymin == 0 && ymax == 0 && radius == 0)
  { fprintf(stderr,"Slit: %s: Warning: Running with CLOSED slit - is this intentional?? \n", NAME_CURRENT_COMP);
}
}

TRACE
%{
  PROP Z0;
  if (((radius == 0) && (x<xmin || x>xmax || y<ymin || y>ymax))
      || ((radius != 0) && (x*x + y*y > radius*radius)))
    WARNON("Slit: %s: Warning: Running with CLOSED slit - is this intentional?? \n", NAME_CURRENT_COMP);
}
}

```

```

[v2.5comps] Slit.comp — [v3.0comps] Slit.comp
Save Undo
[v2.5comps...s] Slit.comp
Slit.comp
Files are identical
Hide

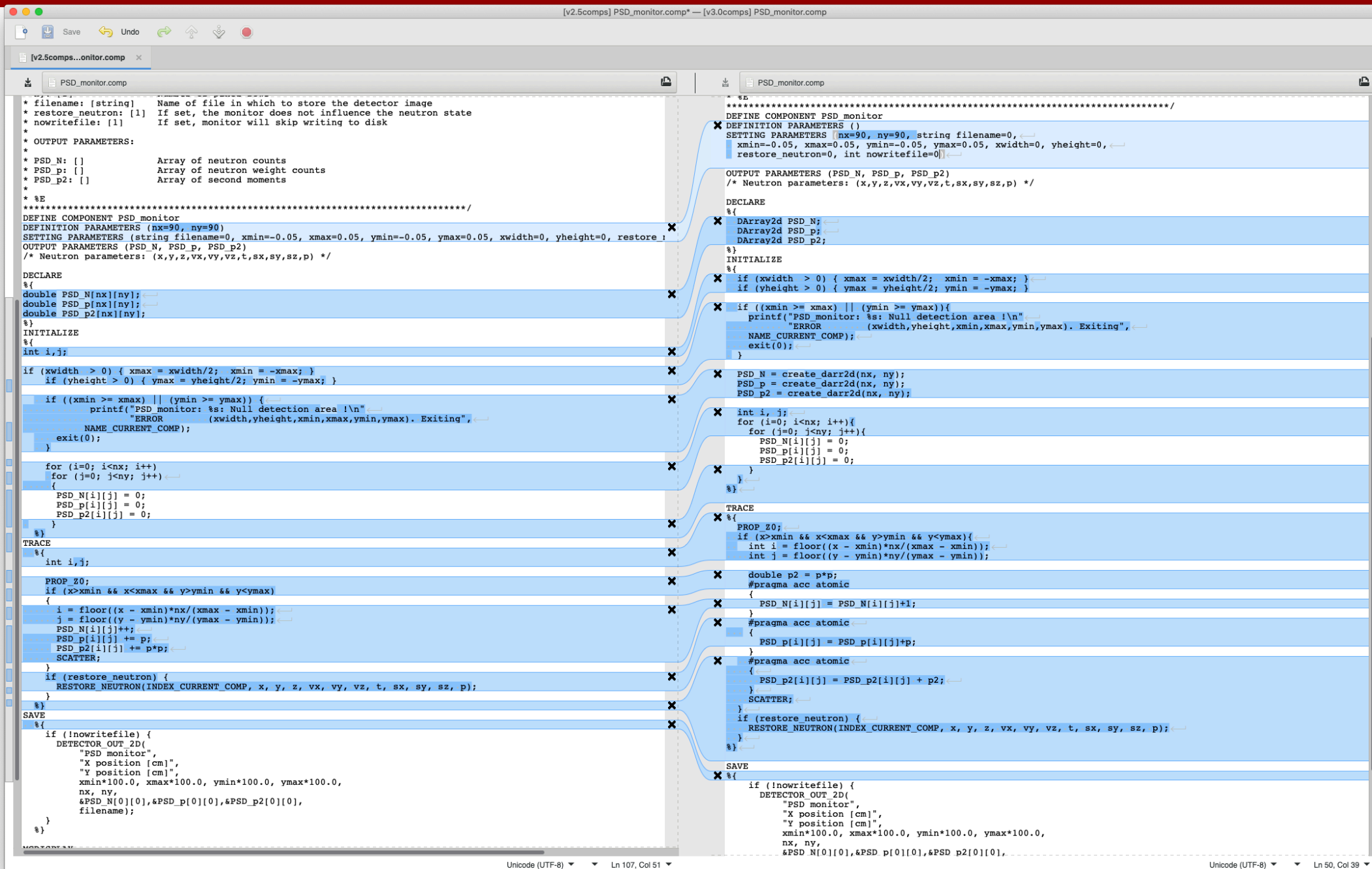
/*****
 * McStas, neutron ray-tracing package
 * Copyright 1997-2002, All rights reserved
 * Risoe National Laboratory, Roskilde, Denmark
 * Institut Laue Langevin, Grenoble, France
 *
 * Component: Slit
 *
 * %I
 * Written by: Kim Lefmann and Henrik M. Roennow
 * Date: June 16, 1997
 * Origin: Risoe
 *
 * Rectangular/circular slit
 *
 * %D
 * A simple rectangular or circular slit. You may either
 * specify the radius (circular shape), or the rectangular bounds.
 * No transmission around the slit is allowed.
 *
 * Example: Slit(xmin=-0.01, xmax=0.01, ymin=-0.01, ymax=0.01)
 *          Slit(xwidth=0.02, yheight=0.02)
 *          Slit(radius=0.01)
 *
 * The Slit will issue a warning if run as "closed"
 *
 * %P
 * INPUT PARAMETERS
 *
 * radius: [m]   Radius of slit in the z=0 plane, centered at Origo
 * xmin: [m]     Lower x bound
 * xmax: [m]     Upper x bound
 * ymin: [m]     Lower y bound
 * ymax: [m]     Upper y bound
 * xwidth: [m]   Width of slit. Overrides xmin,xmax if they are unset.
 * yheight: [m]  Height of slit. Overrides ymin,ymax if they are unset.
 *
 *
 * %E
 *****/

DEFINE COMPONENT Slit
DEFINITION PARAMETERS ( )
  SETTING PARAMETERS (xmin=0, xmax=0, ymin=0, ymax=0, radius=0, xwidth=0, yheight=0)
OUTPUT PARAMETERS ( )
/* Neutron parameters: (x,y,z,vx,vy,vz,t,sx,sy,sz,p) */
INITIALIZE
%{
if (xwidth > 0) {
  if (!xmin && !xmax) {
    xmax=xwidth/2; xmin=-xmax;
  } else {
    fprintf(stderr,"Slit: %s: Error: please specify EITHER xmin & xmax or xwidth\n", NAME_CURRENT_COMP); exit(-1);
  }
}
if (yheight > 0) {
  if (!ymin && !ymax) {
    ymax=yheight/2; ymin=-ymax;
  } else {
    fprintf(stderr,"Slit: %s: Error: please specify EITHER ymin & ymax or ywidth\n", NAME_CURRENT_COMP); exit(-1);
  }
}
if (xmin == 0 && xmax == 0 && ymin == 0 && ymax == 0 && radius == 0)
  { fprintf(stderr,"Slit: %s: Warning: Running with CLOSED slit - is this intentional?? \n", NAME_CURRENT_COMP);
}
}

TRACE
%{
  PROP Z0;
  if (((radius == 0) && (x<xmin || x>xmax || y<ymin || y>ymax))
      || ((radius != 0) && (x*x + y*y > radius*radius)))
    WARNON("Slit: %s: Warning: Running with CLOSED slit - is this intentional?? \n", NAME_CURRENT_COMP);
}
}

```

# PSD lots of changes



```

* filename: [string] Name of file in which to store the detector image
* restore_neutron: [1] If set, the monitor does not influence the neutron state
* nowritefile: [1] If set, monitor will skip writing to disk
*
* OUTPUT PARAMETERS:
*
* PSD_N: [] Array of neutron counts
* PSD_p: [] Array of neutron weight counts
* PSD_p2: [] Array of second moments
*
* %E
*****
DEFINE COMPONENT PSD_monitor
DEFINITION PARAMETERS (nx=90, ny=90)
SETTING PARAMETERS (string filename=0, xmin=-0.05, xmax=0.05, ymin=-0.05, ymax=0.05, xwidth=0, yheight=0, restore_neutron=1, nowritefile=1)
OUTPUT PARAMETERS (PSD_N, PSD_p, PSD_p2)
/* Neutron parameters: (x,y,z,vx,vy,vz,t,sx,sy,sz,p) */

DECLARE
%{
double PSD_N[nx][ny];
double PSD_p[nx][ny];
double PSD_p2[nx][ny];
%}
INITIALIZE
%{
int i,j;

if (xwidth > 0) { xmax = xwidth/2; xmin = -xmax; }
if (yheight > 0) { ymax = yheight/2; ymin = -ymax; }

if ((xmin >= xmax) || (ymin >= ymax)) {
printf("PSD_monitor: %s: Null detection area !\n",
"ERROR (xwidth,yheight,xmin,xmax,ymin,ymax). Exiting",
NAME_CURRENT_COMP);
exit(0);
}

for (i=0; i<nx; i++)
for (j=0; j<ny; j++)
{
PSD_N[i][j] = 0;
PSD_p[i][j] = 0;
PSD_p2[i][j] = 0;
}
%}
TRACE
%{
int i,j;

PROP_Z0;
if (x>xmin && x<xmax && y>ymin && y<ymax)
{
i = floor((x - xmin)*nx/(xmax - xmin));
j = floor((y - ymin)*ny/(ymax - ymin));
PSD_N[i][j]++;
PSD_p[i][j] += p;
PSD_p2[i][j] += p*p;
SCATTER;
}
if (restore_neutron) {
RESTORE_NEUTRON(INDEX_CURRENT_COMP, x, y, z, vx, vy, vz, t, sx, sy, sz, p);
}
%}
SAVE
%{
if (!nowritefile) {
DETECTOR_OUT_2D(
"PSD_monitor",
"X position [cm]",
"Y position [cm]",
xmin*100.0, xmax*100.0, ymin*100.0, ymax*100.0,
nx, ny,
&PSD_N[0][0], &PSD_p[0][0], &PSD_p2[0][0],
filename);
}
%}
}

*****
DEFINE COMPONENT PSD_monitor
DEFINITION PARAMETERS (nx=90, ny=90)
SETTING PARAMETERS (nx=90, ny=90, string filename=0, xmin=-0.05, xmax=0.05, ymin=-0.05, ymax=0.05, xwidth=0, yheight=0, restore_neutron=0, int nowritefile=0)
OUTPUT PARAMETERS (PSD_N, PSD_p, PSD_p2)
/* Neutron parameters: (x,y,z,vx,vy,vz,t,sx,sy,sz,p) */

DECLARE
%{
DArray2d PSD_N;
DArray2d PSD_p;
DArray2d PSD_p2;
%}
INITIALIZE
%{
if (xwidth > 0) { xmax = xwidth/2; xmin = -xmax; }
if (yheight > 0) { ymax = yheight/2; ymin = -ymax; }

if ((xmin >= xmax) || (ymin >= ymax)){
printf("PSD_monitor: %s: Null detection area !\n",
"ERROR (xwidth,yheight,xmin,xmax,ymin,ymax). Exiting",
NAME_CURRENT_COMP);
exit(0);
}

PSD_N = create_darr2d(nx, ny);
PSD_p = create_darr2d(nx, ny);
PSD_p2 = create_darr2d(nx, ny);

int i, j;
for (i=0; i<nx; i++){
for (j=0; j<ny; j++){
PSD_N[i][j] = 0;
PSD_p[i][j] = 0;
PSD_p2[i][j] = 0;
}
}
%}
TRACE
%{
PROP_Z0;
if (x>xmin && x<xmax && y>ymin && y<ymax){
int i = floor((x - xmin)*nx/(xmax - xmin));
int j = floor((y - ymin)*ny/(ymax - ymin));

double p2 = p*p;
#pragma acc atomic
{
PSD_N[i][j] = PSD_N[i][j]+1;
}
#pragma acc atomic
{
PSD_p[i][j] = PSD_p[i][j]+p;
}
#pragma acc atomic
{
PSD_p2[i][j] = PSD_p2[i][j] + p2;
}
SCATTER;
}
if (restore_neutron) {
RESTORE_NEUTRON(INDEX_CURRENT_COMP, x, y, z, vx, vy, vz, t, sx, sy, sz, p);
}
%}
SAVE
%{
if (!nowritefile) {
DETECTOR_OUT_2D(
"PSD_monitor",
"X position [cm]",
"Y position [cm]",
xmin*100.0, xmax*100.0, ymin*100.0, ymax*100.0,
nx, ny,
&PSD_N[0][0], &PSD_p[0][0], &PSD_p2[0][0],
filename);
}
%}
}

```

# PSD lots of changes

No more DEFINITION PARAMETERS

```

* %E
*****/
DEFINE COMPONENT PSD_monitor
DEFINITION PARAMETERS (nx=90, ny=90)
SETTING PARAMETERS (string filename=0, xmin=-0.05, xmax=0.05, ymin=-0.05, ymax=0.05, xwidth=0, yheight=0, restore_neutron=0, int nowritefile=0)
OUTPUT PARAMETERS (PSD_N, PSD_p, PSD_p2)
/* Neutron parameters: (x,y,z,vx,vy,vz,t,sx,sy,sz,p) */

DECLARE
%{
double PSD_N[nx][ny];
double PSD_p[nx][ny];
double PSD_p2[nx][ny];
%}
INITIALIZE
%{

```

```

*****
DEFINE COMPONENT PSD_monitor
DEFINITION PARAMETERS ( )
SETTING PARAMETERS (nx=90, ny=90, string filename=0,
xmin=-0.05, xmax=0.05, ymin=-0.05, ymax=0.05, xwidth=0, yheight=0,
restore_neutron=0, int nowritefile=0)
OUTPUT PARAMETERS (PSD_N, PSD_p, PSD_p2)
/* Neutron parameters: (x,y,z,vx,vy,vz,t,sx,sy,sz,p) */

DECLARE
%{
DArray2d PSD_N;
DArray2d PSD_p;
DArray2d PSD_p2;
%}

```

Use of new DArray2d for dynamic allocation

# PSD lots of changes

```
TRACE
%{
  int i,j;

  PROP_Z0;
  if (x>xmin && x<xmax && y>ymin && y<ymax)
  {
    i = floor((x - xmin)*nx/(xmax - xmin));
    j = floor((y - ymin)*ny/(ymax - ymin));
    PSD_N[i][j]++;
    PSD_p[i][j] += p;
    PSD_p2[i][j] += p*p;
    SCATTER;
  }
  if (restore_neutron) {
    RESTORE_NEUTRON(INDEX_CURRENT_COMP, x, y, z, vx, vy, vz, t, sx, sy, sz, p);
  }
}%
```

```
TRACE
%{
  PROP_Z0;
  if (x>xmin && x<xmax && y>ymin && y<ymax){
    int i = floor((x - xmin)*nx/(xmax - xmin));
    int j = floor((y - ymin)*ny/(ymax - ymin));

    double p2 = p*p;
    #pragma acc atomic
    {
      PSD_N[i][j] = PSD_N[i][j]+1;
    }
    #pragma acc atomic
    {
      PSD_p[i][j] = PSD_p[i][j]+p;
    }
    #pragma acc atomic
    {
      PSD_p2[i][j] = PSD_p2[i][j] + p2;
    }
    SCATTER;
  }
  if (restore_neutron) {
    RESTORE_NEUTRON(INDEX_CURRENT_COMP, x, y, z, vx, vy, vz, t, sx, sy, sz, p);
  }
}%
```

Enabling atomic writes on the detector arrays



```
PROP_Z0;
if (x>xmin && x<xmax && y>ymin && y<ymax){
  int i = floor((x - xmin)*nx/(xmax - xmin));
  int j = floor((y - ymin)*ny/(ymax - ymin));

  double p2 = p*p;
  #pragma acc atomic
  {
    PSD_N[i][j] = PSD_N[i][j]+1;
  }
  #pragma acc atomic
  {
    PSD_p[i][j] = PSD_p[i][j]+p;
  }
  #pragma acc atomic
  {
    PSD_p2[i][j] = PSD_p2[i][j] + p2;
  }
  SCATTER;
}
```



EUROPEAN SPALLATION SOURCE

# Generated code: LOTS of changes

example\_v25.c — example\_v30.c

```

example_v25.c
/* Automatically generated file. Do not edit.
 * Format: ANSI C source code
 * Creator: McStas <http://www.mcstas.org>
 * Instrument: example_v25.instr (Minimal)
 * Date: Fri Jan 17 14:24:26 2020
 * File: example_v25.c
 * Compile: cc -o Minimal.out example_v25.c
 * CFLAGS=
 */

#define MCCODE_STRING "McStas 2.5 - Dec. 12, 2018"
#define FLAVOR "mcstas"
#define FLAVOR_UPPER "MCSTAS"
#define MC_USE_DEFAULT_MAIN
#define MC_EMBEDDED_RUNTIME

#line 1 "mccode-r.h"
/*****
 *
 * McCode, neutron/xray ray-tracing package
 * Copyright (C) 1997-2009, All rights reserved
 * Risoe National Laboratory, Roskilde, Denmark
 * Institut Laue Langevin, Grenoble, France
 *
 * Runtime: share/mccode-r.h
 *
 * %Identification
 * Written by: KN
 * Date: Aug 29, 1997
 * Release: McStas 2.5
 * Version: $Revision$
 *
 * Runtime system header for McStas/McXtrace.
 *
 * In order to use this library as an external library, the following variables
 * and macros must be declared (see details in the code)
 *
 * struct mcinputtable struct mcinputtable[];
 * int mcinumpar;
 * char mcinstrument_name[], mcinstrument_source[];
 * int mctraceenabled, mcdefaultmain;
 * extern MCNUM mccomp_storein[];
 * extern MCNUM mcAbsorbProp[];
 * extern MCNUM mcScattered;
 * #define MCCODE_STRING "the McStas/McXtrace version"
 *
 * Usage: Automatically embedded in the c code.
 *
 * $Id$
 *****/

#ifndef MCCODE_R_H
#define MCCODE_R_H "$Revision$"

#include <math.h>
#include <string.h>
#include <stdlib.h>
#include <stdio.h>
#include <stdarg.h>
#include <limits.h>
#include <errno.h>
#include <time.h>
#include <float.h>
#include <inttypes.h>

/* If the runtime is embedded in the simulation program, some definitions can
   be made static. */

#ifdef MC_EMBEDDED_RUNTIME
#define mcstatic static
#else
#define mcstatic
#endif

#ifdef dest_os
#if ( _dest_os == __mac_os )
#define MAC

```

example\_v30.c

```

/* Automatically generated file. Do not edit.
 * Format: ANSI C source code
 * Creator: McStas <http://www.mcstas.org>
 * Instrument: example_v30.instr (Minimal)
 * Date: Fri Jan 17 15:13:01 2020
 * File: example_v30.c
 * CFLAGS=
 */

#define MCCODE_STRING "McStas 3.0-dev - Jan. 17, 2020"
#define FLAVOR "mcstas"
#define FLAVOR_UPPER "MCSTAS"

#define MC_USE_DEFAULT_MAIN
#define PI 3.14159265358979323846
#ifdef M_PI
#define M_PI PI
#endif
#ifdef M_2_PI
#define M_2_PI 0.63661977236758134308
#endif
#ifdef M_PI_2
#define M_PI_2 1.57079632679489661923 /* pi/2 */
#endif
#ifdef M_SQRT2
#define M_SQRT2 1.4142135623730951 /* sqrt(2) */
#endif

#ifdef DISABLE_TRACE
#undef MC_TRACE_ENABLED
#endif

#ifdef USE_PGI
#undef MC_TRACE_ENABLED
#include <openacc_curand.h>
#endif

struct _struct_particle {
  double x,y,z; /* position [m] */
  double vx,vy,vz; /* velocity [m/s] */
  double sx,sy,sz; /* spin [0-1] */
  unsigned long randstate[7];
  double t, p; /* time, event weight */
  long long uid; /* event ID */
  long _index; /* component index where to send this event */
  long _absorbed; /* flag set to TRUE when this event is to be removed/ignored */
  long _scattered; /* flag set to TRUE when this event has interacted with the last component instance */
  long _restore; /* set to true if neutron event must be restored */
  // user variables:
  double flag;
};
typedef struct _struct_particle_class_particle;

_class_particle _particle_global_randnbuse_var;
_class_particle* _particle = &_particle_global_randnbuse_var;

#define MC_EMBEDDED_RUNTIME
/* embedding file "mccode-r.h" */

/*****
 *
 * McCode, neutron/xray ray-tracing package
 * Copyright (C) 1997-2009, All rights reserved
 * Risoe National Laboratory, Roskilde, Denmark
 * Institut Laue Langevin, Grenoble, France
 *
 * Runtime: share/mccode-r.h
 *
 * %Identification
 * Written by: KN
 * Date: Aug 29, 1997
 * Release: McStas 3.0-dev
 * Version: $Revision$
 *
 * Runtime system header for McStas/McXtrace.
 *
 * In order to use this library as an external library, the following variables
 * and macros must be declared (see details in the code)
 *
 * struct mcinputtable struct mcinputtable[];
 * int mcinumpar;
 * char mcinstrument_name[], mcinstrument_source[];
 * int mctraceenabled, mcdefaultmain;
 * extern MCNUM mccomp_storein[];
 * extern MCNUM mcAbsorbProp[];
 * extern MCNUM mcScattered;
 * #define MCCODE_STRING "the McStas/McXtrace version"
 *
 * Usage: Automatically embedded in the c code.
 *
 * $Id$
 *****/

#ifndef MCCODE_R_H
#define MCCODE_R_H "$Revision$"

#include <math.h>
#include <string.h>
#include <stdlib.h>
#include <stdio.h>
#include <stdarg.h>
#include <limits.h>
#include <errno.h>
#include <time.h>
#include <float.h>
#include <inttypes.h>

/* If the runtime is embedded in the simulation program, some definitions can
   be made static. */

#ifdef MC_EMBEDDED_RUNTIME
#define mcstatic static
#else
#define mcstatic
#endif

#ifdef dest_os
#if ( _dest_os == __mac_os )
#define MAC

```

# The neutron and “state-flags” in the instrument

v2.5: Global variables

```
double x, y, z, vx, vy, vz, t, sx, sy, sz, p;    double flag;
```

v3.0: particle struct, including any USERVARS like flag.

```
struct _struct_particle {  
    double x,y,z; /* position [m] */  
    double vx,vy,vz; /* velocity [m/s] */  
    double sx,sy,sz; /* spin [0-1] */  
    unsigned long randstate[7];  
    double t, p; /* time, event weight */  
    long long _uid; /* event ID */  
    long _index; /* component index where to send this event */  
    long _absorbed; /* flag set to TRUE when this event is to be removed/ignored */  
    long _scattered; /* flag set to TRUE when this event has interacted with the last component instance */  
    long _restore; /* set to true if neutron event must be restored */  
    // user variables:  
    double flag;  
};  
typedef struct _struct_particle _class_particle;
```



# Input parameters and the instrument struct

```

struct _struct_instrument_parameters {
    MCNUM _dummy;
};
typedef struct _struct_instrument_parameters _class_instrument_parameters;

struct _instrument_struct {
    char _name[256]; /* the name of this instrument e.g. 'Minimal' */
    /* Counters per component instance */
    double counter_AbsorbProp[6]; /* absorbed events in PROP routines */
    double counter_N[6], counter_P[6], counter_P2[6]; /* event counters after each component instance */
    _class_particle _trajectory[6]; /* current trajectory for STORE/RESTORE */
    /* Components position table (absolute and relative coords) */
    Coords _position_relative[6]; /* positions of all components */
    Coords _position_absolute[6];
    _class_instrument_parameters _parameters; /* instrument parameters */
} _instrument_var;
struct _instrument_struct *instrument = & _instrument_var;

```

... in e.g. an EXTEND section one should now use the macro INSTRUMENT\_GETPAR(dummy) which translates the bare dummy into instrument->\_parameters.\_dummy

```
#define INSTRUMENT_GETPAR(par) (instrument->_parameters._ ## par)
```

# Declare section

```
/* User declarations from instrument definition. Can define functions. */
double constant;
double two_x_dummy;
```

# Initialise section

```
#define dummy (instrument->_parameters._dummy)
{
  constant=2;
  two_x_dummy=2*dummy;
}
```

```
#undef dummy
_arm_setpos(); /* type Arm */
_source_setpos(); /* type Source_simple */
_coll2_setpos(); /* type Slit */
_detector_setpos(); /* type PSD_monitor */
```

```
/* call iteratively all components INITIALISE */
```

```
class_Source_simple_init(&_source_var);
```

```
class_Slit_init(&_coll2_var);
```

```
class_PSD_monitor_init(&_detector_var);
```



Functions per component with  
related component structs

# Component struct example

```

/* component detector=PSD_monitor() [4] DECLARE */
/* Parameter definition for component type 'PSD_monitor' */
struct _struct_PSD_monitor_parameters {
  /* Component type 'PSD_monitor' setting parameters */
  MCNUM nx;
  MCNUM ny;
  char filename[16384];
  MCNUM xmin;
  MCNUM xmax;
  MCNUM ymin;
  MCNUM ymax;
  MCNUM xwidth;
  MCNUM yheight;
  MCNUM restore_neutron;
  long nowritefile;
  /* Component type 'PSD_monitor' private parameters */
  /* Component type 'PSD_monitor' DECLARE code stored as structure members */
  DArray2d PSD_N;
  DArray2d PSD_p;
  DArray2d PSD_p2;
}; /* _struct_PSD_monitor_parameters */
typedef struct _struct_PSD_monitor_parameters _class_PSD_monitor_parameters;

```

Built from component definition

```

/* Parameters for component type 'PSD_monitor' */
struct _struct_PSD_monitor {
  char _name[256]; /* e.g. detector */
  char _type[256]; /* PSD_monitor */
  long _index; /* e.g. 2 index in TRACE list */
  Coords _position_absolute;
  Coords _position_relative; /* wrt PREVIOUS */
  Rotation _rotation_absolute;
  Rotation _rotation_relative; /* wrt PREVIOUS */
  int _rotation_is_identity;
  _class_PSD_monitor_parameters _parameters;
};
typedef struct _struct_PSD_monitor _class_PSD_monitor;
_class_PSD_monitor _detector_var;
#pragma acc declare create ( _detector_var )

```

OpenACC clause to define variable in device scope.

# Component init function example

```

_class_Source_simple *class_Source_simple_init( *_comp ) {
#define radius (_comp->_parameters.radius)
#define yheight (_comp->_parameters.yheight)
#define xwidth (_comp->_parameters.xwidth)
#define dist (_comp->_parameters.dist)
#define focus_xw (_comp->_parameters.focus_xw)
#define focus_yh (_comp->_parameters.focus_yh)
#define E0 (_comp->_parameters.E0)
#define dE (_comp->_parameters.dE)
#define lambda0 (_comp->_parameters.lambda0)
#define dlambd (_comp->_parameters.dlambd)
#define flux (_comp->_parameters.flux)
#define gauss (_comp->_parameters.gauss)
#define target_index (_comp->_parameters.target_index)
#define pmul (_comp->_parameters.pmul)
#define square (_comp->_parameters.square)
#define srcArea (_comp->_parameters.srcArea)
#define tx (_comp->_parameters.tx)
#define ty (_comp->_parameters.ty)
#define tz (_comp->_parameters.tz)
    SIG_MESSAGE("[_source_init] component source=Source_simple() INITIALISE [Source_simple.comp:68]");
    square = 0;
    /* Determine source area */
    if (radius && !yheight && !xwidth ) {
        square = 0;
        srcArea = PI*radius*radius;
    } else if(yheight && xwidth) {
        square = 1;
        srcArea = xwidth * yheight;
    }

    if (flux) {
        pmul=flux*1e4*srcArea/mcget_ncount();
        if (dlambd)
            pmul *= 2*dlambd;
        else if (dE)
            pmul *= 2*dE;
    } else {
        gauss = 0;
        pmul=1.0/(mcget_ncount()*4*PI);
        .... etc
    }
}

```



Contains component initialise  
section

**Instrument and component structs built on CPU and transferred to GPU using OpenACC pragmas at the end of**

**INITIALISE**

```
#ifdef USE_PGI
# include <openacc.h>
acc_attach( (void*)&_arm_var );
acc_attach( (void*)&_source_var );
acc_attach( (void*)&_coll2_var );
acc_attach( (void*)&_detector_var );
#pragma acc update device(_arm_var)
#pragma acc update device(_source_var)
#pragma acc update device(_coll2_var)
#pragma acc update device(_detector_var)
acc_attach( (void*)&_instrument_var );
#pragma acc update device(_instrument_var)
#endif
```



Similar “host” update  
in FINALLY

# Main trace Loop (v1)

```

/* loop to generate events and call raytrace() propagate them */
void raytrace_all(unsigned long long ncount, unsigned long seed) {
|
|  /* CPU-loop */
|  unsigned long long loops;
|  long innerloop=2147483647;
|  loops = ceil((double)ncount/innerloop);
|  if (ncount>innerloop) {
|    printf("Defining %llu CPU loops around kernel and adjusting ncount\n",loops);
|    mcset_ncount(loops*2147483647);
|  } else {
|    loops=1;
|    innerloop = ncount;
|  }
|
|  for (unsigned long long cloop=0; cloop<loops; cloop++) {
|    if (loops>1) fprintf(stdout, "%d..", (int)cloop); fflush(stdout);
|
|    #pragma acc parallel loop
|    for (unsigned long pidx=0 ; pidx < innerloop ; pidx++) {
|      _class_particle particleN = mcgenstate(); // initial particle
|      _class_particle* _particle = &particleN;
|      particleN._uid = pidx;
|
|      long seq = pidx + seed;
|      srandom(_hash(pidx + seed));
|
|      raytrace(_particle);
|    } /* inner for */
|    seed = seed+innerloop;
|  } /* CPU for */
|  printf("\n");
| } /* raytrace_all */

```

CPU may execute  
multiple  
GPU loops

Main parallel pragma that define kernel

Cogen-constructed function with calls  
to component trace functions

# Main trace Loop (v1)

```

#pragma acc routine seq
int raytrace(_class_particle* _particle) { /* single event propagation, called by mccode_main for Minimal:TRACE */

    /* init variables and counters for TRACE */
    #undef ABSORB0
    #undef ABSORB
    #define ABSORB0 do { DEBUG_ABSORB(); MAGNET_OFF; ABSORBED++; return(ABSORBED);} while(0)
    #define ABSORB ABSORB0
    DEBUG_ENTER();
    DEBUG_STATE();
    /* the main iteration loop for one incoming event */
    while (!ABSORBED) { /* iterate event until absorbed */
        _class_particle _particle_save;
        /* send particle event to component instance, one after the other */
        char flag_nocoordschange=0;
        if (!ABSORBED && _particle->_index == 1) {
            /* begin component arm=Arm() [1] */
            if (!flag_nocoordschange) { // flag activated by JUMP to pass coords change
                if (_arm_var._rotation_is_identity) {
                    coords_get(coords_add(coords_set(x,y,z), _arm_var._position_relative),&x, &y, &z);
                } else
                    mccoordschange(_arm_var._position_relative, _arm_var._rotation_relative, _particle);
            } else flag_nocoordschange=0;
            _particle_save = *_particle;
            DEBUG_COMP(_arm_var._name);
            DEBUG_STATE();
            class_Arm_trace(&_arm_var, _particle); /* contains EXTEND code */
            if (_particle->_restore)
                *_particle = _particle_save;
            _particle->_index++;
            if (!ABSORBED) DEBUG_STATE();
        } /* end component arm [1] */
        if (!ABSORBED && _particle->_index == 2) {
            /* begin component source=Source_simple() [2] */
            if (!flag_nocoordschange) { // flag activated by JUMP to pass coords change
                if (_source_var._rotation_is_identity) {
                    coords_get(coords_add(coords_set(x,y,z), _source_var._position_relative),&x, &y, &z);
                } else
                    mccoordschange(_source_var._position_relative, _source_var._rotation_relative, _particle);
            } else flag_nocoordschange=0;
            _particle_save = *_particle;
            DEBUG_COMP(_source_var._name);
            DEBUG_STATE();
            class_Source_simple_trace(&_source_var, _particle);
            if (_particle->_restore)
                *_particle = _particle_save;
            _particle->_index++;
            if (!ABSORBED) DEBUG_STATE();
        } /* end component source [2] */
    }
}

```

Comp 1

Comp 2

# Main trace Loop (v2) potentially “funnelled”

```
void raytrace_all_funnel(unsigned long long ncount, unsigned long seed) {
```

```
    // set up outer (CPU) loop / particle batches
    unsigned long long loops;
    long innerloop=1024*1024; // <-- tune by memory capacity here (max threads: 2147483647);
    loops = ceil((double)ncount/innerloop);
    if (ncount>innerloop) {
        printf("Defining %llu CPU loops around kernel and adjusting ncount\n",loops);
        mcset_ncount(loops*2147483647);
    } else {
        loops=1;
        innerloop = ncount;
    }
}
```

← Smaller “innerloop” due to memory needs for the array of “particles” etc.

```
    // outer loop / particle batches
    for (unsigned long long cloop=0; cloop<loops; cloop++) {
        if (loops>1) fprintf(stdout, "%d..", (int)clloop); fflush(stdout);
    }
```

```
    // create particles memory block and pointer array (buffer and sorted)
    #ifdef USE_PGI
        _class_particle* particles = acc_malloc(innerloop*sizeof(_class_particle));
    #else
        _class_particle* particles = malloc(innerloop*sizeof(_class_particle));
    #endif
    #pragma acc enter data create(particles[0:innerloop])
    // TODO: _class_particle** psorted = malloc(innerloop*sizeof(_class_particle*));
    // TODO: _class_particle** pBuffer = malloc(innerloop*sizeof(_class_particle*));
}
```

← Allocation of particle array

← “fill” the array and make it available to GPU

```
    // TODO: do we need a GPU data section for the above buffers here?
```

```
    // set up, generate particles
    #pragma acc parallel loop present(particles)
    for (unsigned long pidx=0 ; pidx < innerloop ; pidx++) {
        // generate particle state, set loop index and seed
        particles[pidx] = mcgenstate();
        _class_particle* _particle = particles + pidx;
        _particle->uid = pidx;
        srandom(_hash(pidx + seed)); // _particle->state usage built into srandom macro
    }
}
```

← Initialise / generate particles GPU side

```
    // iterate components
```

```
    //TODO: innerloop = sort_absorb_last(particles, innerloop);
```



# Main trace Loop (v2) potentially “funnelled”

```

// arm
#pragma acc parallel loop present(particles)
for (unsigned long pidx=0 ; pidx < innerloop ; pidx++) {
    _class_particle* _particle = particles + pidx;
    _class_particle _particle_save;
    if (!ABSORBED) {
        if (_arm_var._rotation_is_identity)
            coords_get(coords_add(coords_set(x,y,z), _arm_var._position_relative),&x, &y, &z);
        else
            mccoordschange(_arm_var._position_relative, _arm_var._rotation_relative, _particle);
        _particle_save = *_particle;
        class_Arm_trace(&_arm_var, _particle); /* contains EXTEND code */
        if (_particle->_restore)
            *_particle = _particle_save;
        _particle->_index++;
    }
}

```

Comp 1 in independent kernel

//TODO: innerloop = sort\_absorb\_last(particles, innerloop);

← One would then get rid of ABSORB'ed particles, do SPLITS here

```

// source
#pragma acc parallel loop present(particles)
for (unsigned long pidx=0 ; pidx < innerloop ; pidx++) {
    _class_particle* _particle = particles + pidx;
    _class_particle _particle_save;
    if (!ABSORBED) {
        if (_source_var._rotation_is_identity)
            coords_get(coords_add(coords_set(x,y,z), _source_var._position_relative),&x, &y, &z);
        else
            mccoordschange(_source_var._position_relative, _source_var._rotation_relative, _particle);
        _particle_save = *_particle;
        class_Source_simple_trace(&_source_var, _particle);
        if (_particle->_restore)
            *_particle = _particle_save;
        _particle->_index++;
    }
}

```

Comp 2 in independent kernel

# Both trace approaches execute the normal component trace function, example:

```
#pragma acc routine seq
_class_Source_simple *class_Source_simple_trace(_class_Source_simple *_comp
, _class_particle *_particle) {
  ABSORBED=SCATTERED=RESTORE=0;
```

```
#define radius (_comp->_parameters.radius)
#define yheight (_comp->_parameters.yheight)
#define xwidth (_comp->_parameters.xwidth)
#define dist (_comp->_parameters.dist)
#define focus_xw (_comp->_parameters.focus_xw)
#define focus_yh (_comp->_parameters.focus_yh)
#define E0 (_comp->_parameters.E0)
#define dE (_comp->_parameters.dE)
#define lambda0 (_comp->_parameters.lambda0)
#define dlambda (_comp->_parameters.dlambda)
#define flux (_comp->_parameters.flux)
#define gauss (_comp->_parameters.gauss)
#define target_index (_comp->_parameters.target_index)
#define pmul (_comp->_parameters.pmul)
#define square (_comp->_parameters.square)
#define srcArea (_comp->_parameters.srcArea)
#define tx (_comp->_parameters.tx)
#define ty (_comp->_parameters.ty)
#define tz (_comp->_parameters.tz)
  SIG_MESSAGE("[_source_trace] component source=Source_simple() TRACE [Source_simple.comp:127]");
  double chi,E,lambda,v,r, xf, yf, rf, dx, dy, pdir;
```

```
t=0;
z=0;
```

```
if (square == 1) {
  x = xwidth * (rand01() - 0.5);
  y = yheight * (rand01() - 0.5);
} else {
  chi=2*PI*rand01();
  r=sqrt(rand01())*radius;
  x=r*cos(chi);
  y=r*sin(chi);
}
randvec_target_rect_real(&xf, &yf, &rf, &pdir,
  .... etc tx, ty, tz, focus_xw, focus_yh, ROT_A_CURRENT_COMP, x, y, z, 2);
```



Contains component trace section

# Pro's and cons

- V1 in general parallelises well, but SPLITS may not be easy to do
- V2 is slower due to multiple kernels and related memory transfer overhead (?). Allows SPLIT
- We are thinking if we should do V3 “best of both worlds”, i.e. multiple kernels only when SPLIT is introduced, each SPLIT infers a problem-reduction and another kernel
- Underlying component code identical, only changes in the code generation needed

# Pragmas and libs used

```

#include <accelmath.h>
#pragma acc declare create ( mcgravitation )
#pragma acc declare create ( mcseed )
#pragma acc declare create ( mcgravitation )
#pragma acc declare create ( mcMagnet )
#pragma acc declare create ( mcallowbackprop )
#pragma acc declare create ( mcncount )
#pragma acc routine seq
#pragma acc routine sequential
#pragma acc declare create ( _instrument_var )
#pragma acc declare create ( instrument )
#pragma acc declare create ( _arm_var )
#pragma acc declare create ( _source_var )
#pragma acc declare create ( _coll2_var )
#pragma acc declare create ( _detector_var )
# include <openacc.h>
acc_attach( (void*)&_arm_var );
acc_attach( (void*)&_source_var );
acc_attach( (void*)&_coll2_var );
acc_attach( (void*)&_detector_var );
#pragma acc update device(_arm_var)
#pragma acc update device(_source_var)
#pragma acc update device(_coll2_var)
#pragma acc update device(_detector_var)
acc_attach( (void*)&_instrument_var );
#pragma acc update device(_instrument_var)
#pragma acc routine seq
#pragma acc atomic
#pragma acc parallel loop
#pragma acc declare device_resident(particles)
_class_particle* particles = acc_malloc(innerloop*sizeof(_class_particle));
#pragma acc enter data create(particles[0:innerloop])
#pragma acc parallel loop present(particles)
acc_free(particles);
#pragma acc update host(_arm_var)
#pragma acc update host(_source_var)
#pragma acc update host(_coll2_var)
#pragma acc update host(_detector_var)
#pragma acc update host(_instrument_var)

```

“math.h on GPU”

Needed basic variables / flags

GPUify all functions to be executed on GPU, i.e. in TRACE

Global instrument struct and component structs, including members like detector arrays etc.

OpenACC pure c-code, e.g. for the attaches (pointer-setup)

Ensure GLOBAL structs updated GPU-side end of INITIALISE

GPUify all functions to be executed on GPU, i.e. in TRACE anything written to by multiple threads (detectors) should be “atomic”

Loop V1

Loop V2

Ensure GLOBAL structs updated host-side start of FINALLY

# New RNG 'KISS'

- We couldn't easily port Mersenne Twister
- Experimenting with curand showed huge overhead for our relative small number of random numbers
- An RNG 'state' carried with each particle - bonus: same seed gives same numbers even when comparing between CPU and GPU
- Required patching prototype of ALL functions making use of e.g. rand01()

# Compiler settings used

`pgcc -ta=tesla,managed,deepcopy -Minfo=accel -DUSE_PGI -DNOSIGNALS -DRNG_ALG=2`



Generate Tesla code. "compute capability" e.g. `tesla:cc70` may be specified to indicate specific card.

Use CUDA shared memory for host-device-host allocation. Needed for our 2D-arrays at present, may include penalty, we could get rid.

Used to indicate that copies of variables should be 'deep', e.g. for our structs. (... but removing it seems to have little / no influence?)

Give accel debug information

Main "enable GPU" switch

Disable our signal handling, e.g. USR2 for save. Also the case in our MPI implementation.

Use our new KISS rng



# McStas heading for the GPU... November 2019

9 instruments fully ported, also realistic ones like PSI\_DMC\*

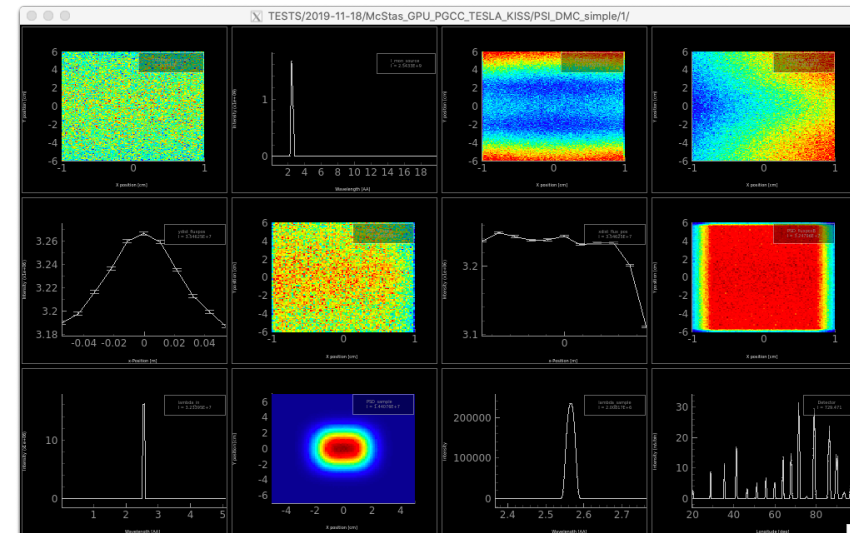
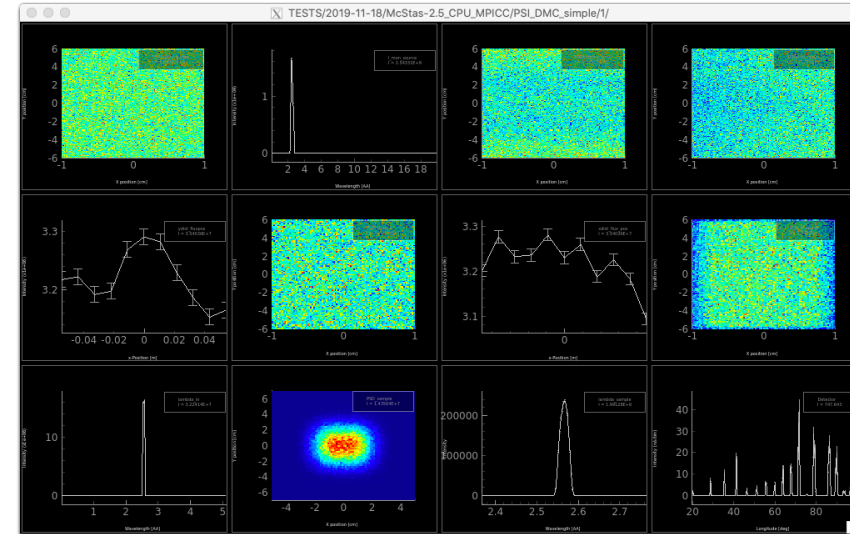
10-core MPI run,  
1e7 in 2 secs



Tesla V100 run,  
1e9 in 22 secs



~ i.e. 2 orders of magnitude wrt. a single, modern CPU core

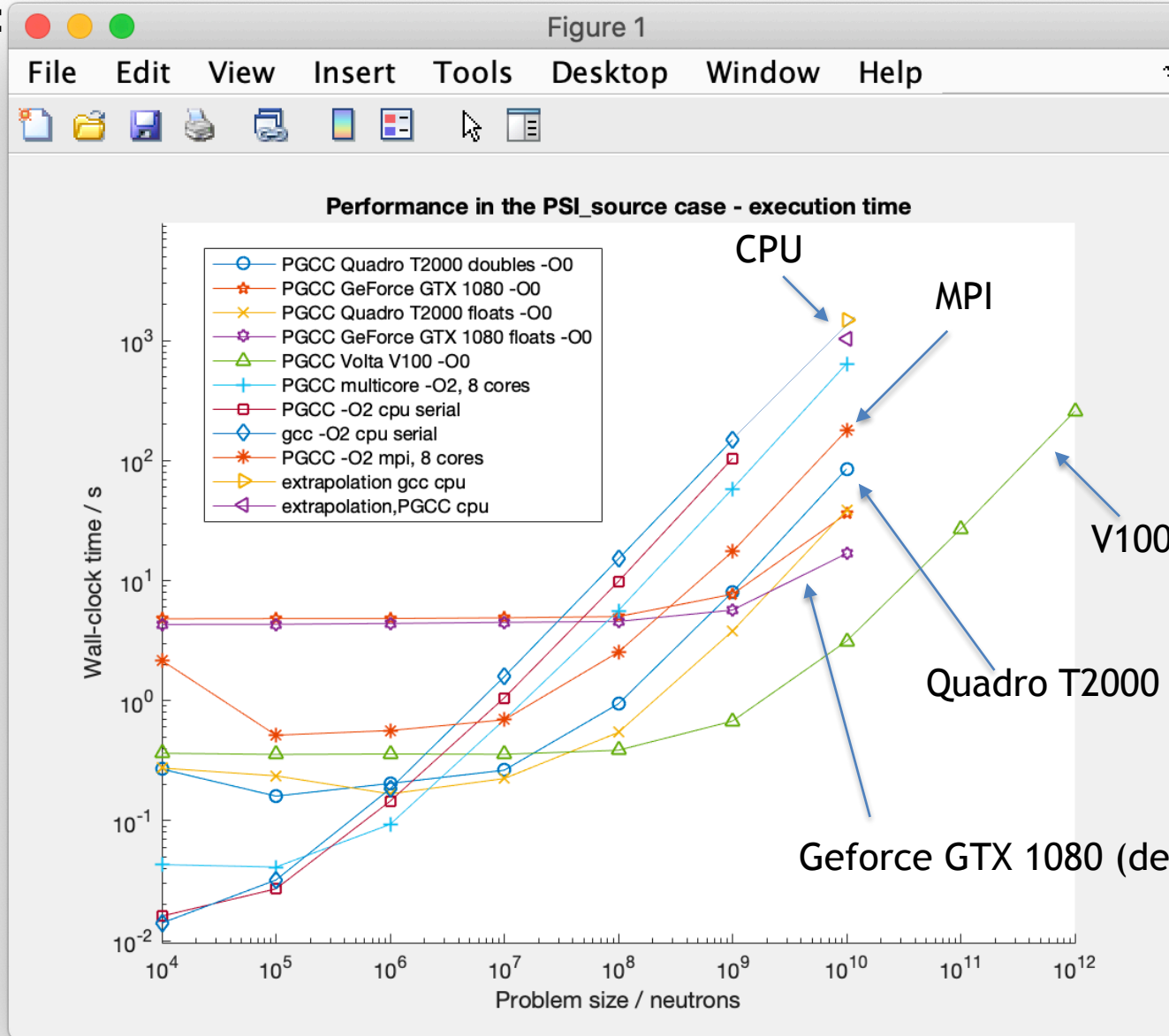


\*Guide component without reflection-file support, SPLIT disabled, OFF geometry disabled

## Wallclocks:

**Idealised instrument** with source and monitor only - i.e. without any use of the ABSORB macro.

(Likely a good indication of maximal speedup achievable.)

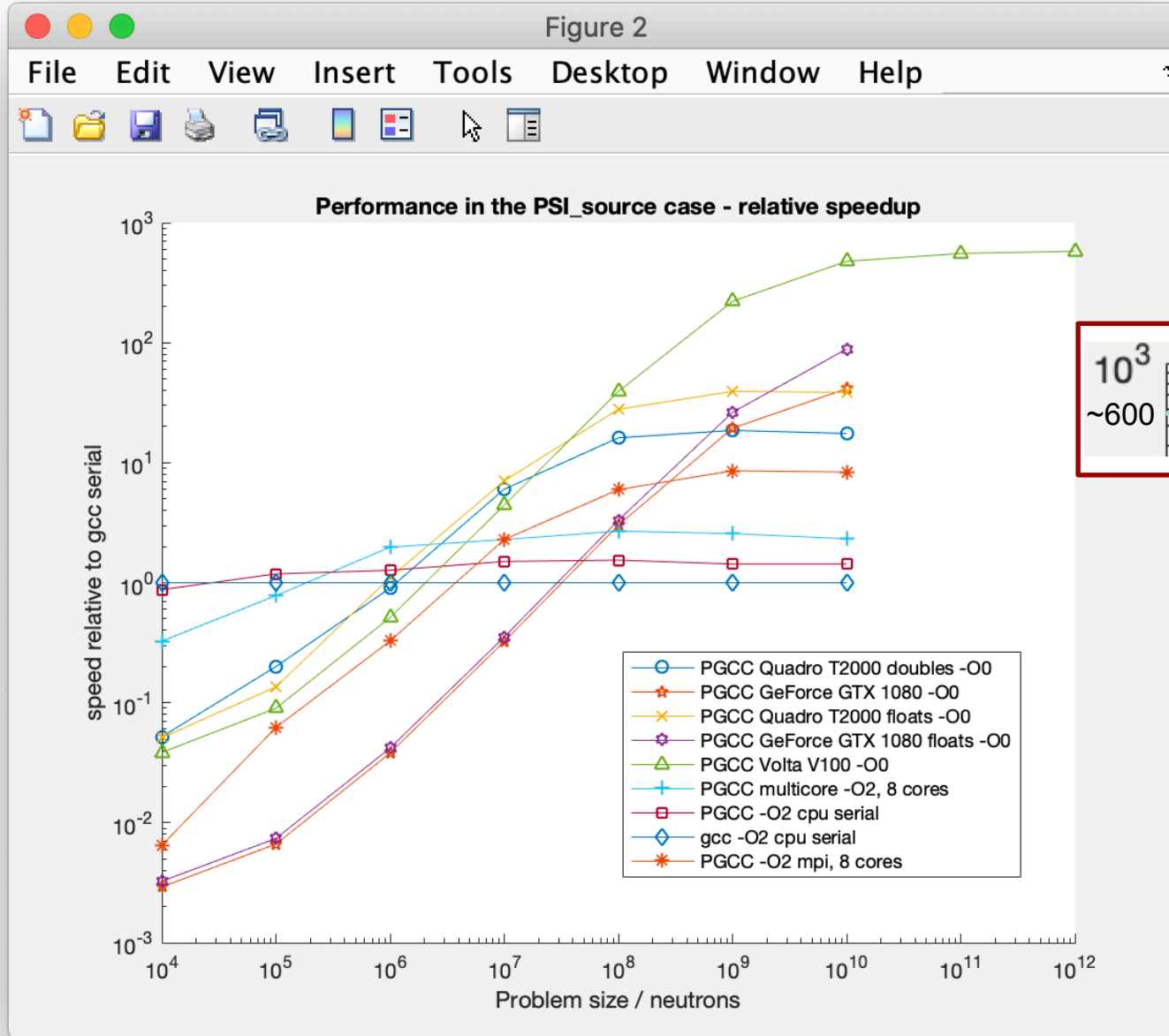




Speedup:

**Idealised instrument** with source and monitor only - i.e. without any use of the ABSORB macro.

(Likely a good indication of maximal speedup achievable.)



Looks like a factor of ~600



Renormalised to wall-clock of single-core gcc standard simulation

# McStas heading for the GPU... December 2019 - today's compilation status:

Numerical output with graphics:

[http://new-nightly.mccode.org/2019-12-06/2019-12-06\\_output.html](http://new-nightly.mccode.org/2019-12-06/2019-12-06_output.html)

Statistics:

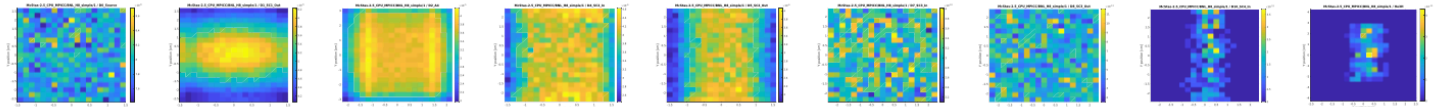
<http://new-nightly.mccode.org/2019-12-06/stats.txt>

(38 of 142 instruments, 62 of 207 components)

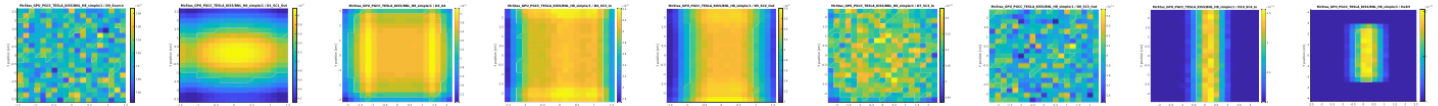
## BNL\_H8\_simple/1 - comparison McStas-2.5\_CPU\_MPICC vs McStas\_GPU\_PGCC\_TESLA\_KISS

[\(Click to access files\)](#)

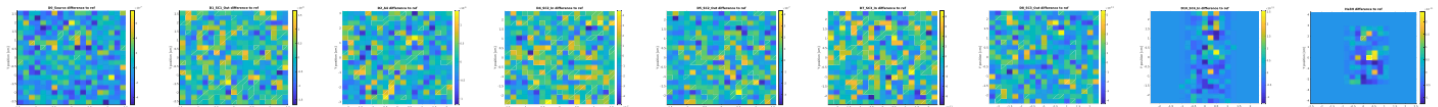
### McStas-2.5\_CPU\_MPICC (reference)



### McStas\_GPU\_PGCC\_TESLA\_KISS



### Difference



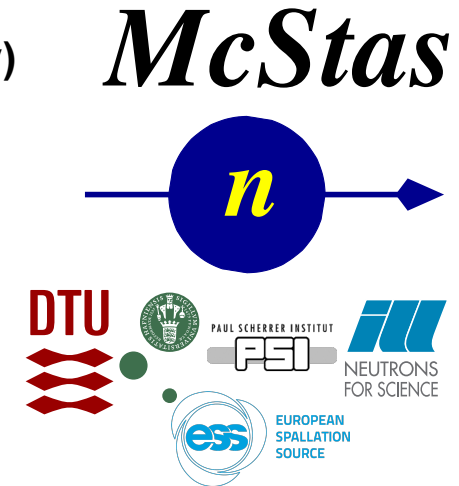
test results

ref user: pkwi

	McStas-2.5_CPU_MPICC (ref) - 1e7 n-62-23-6 Intel(R) Xeon(R) CPU E5-2680 v2 @ 2.80GHz 20191120_0127_38	McStas_CPU_GCC_KISS - 1e6 n-62-21-99 Intel(R) Xeon(R) CPU E5-2650 v4 @ 2.20GHz 20191205_0058_36	McStas_CPU_GCC_MT - 1e6 n-62-21-99 Intel(R) Xeon(R) CPU E5-2650 v4 @ 2.20GHz 20191205_0122_14	McStas_CPU_MPICC_KISS - 1e7 n-62-23-9 Intel(R) Xeon(R) CPU E5-2680 v2 @ 2.80GHz 20191205_0034_53	McStas_GPU_PGCC_TESLA_KISS - 1e9 n-62-20-6 Intel(R) Xeon(R) Gold 6126 CPU @ 2.60GHz Tesla V100-PCIE-16GB 20191205_0012_04
BNL_H8_simple	5.80 s   1.99 s   9.7e-10   99%	4.32 s   1.03 s   1.3e-09   136%	4.35 s   0.99 s   1e-09   106%	4.11 s   1.50 s   1.1e-09   110%	17.59 s   8.16 s   9.7e-10   98%

## McStas 3.0 - next generation code generator - release plans

- Limited-functionality “beta” release to be made public soon (jan-mar) after **2.6 (january)**
  - Expect bugs!
  - Only a subset of components / instruments
  - Event interchange with 2.6 possible via MCPL
- Main purpose: **get this working in ‘the wild’**
  - Your instruments will likely **require (limited) rewriting**
    - Your instruments will need USERVARS for flags that change with each neutron
  - Your own components will **likely require rewriting**
    - Support for DEFINITION PARAMETERS is deprecated. Use the new string, vector, ... instead
    - New macro MC\_GETPAR2 needed to access other component scopes (NOT via defines)
    - E.g. the declare section **cannot include assignments**
    - Arrays must be declared/initialized using a new set of functions (i.e. not double PSD\_I[nx][ny] with definition parms)
- Hence some backward compatibility is lost and we need **to increment major release #**



# McStas 3.0 - next generation code generator - code camp

## January 27th-31st in Copenhagen

- **Code-camp participants:**
  - **McStas-McXtrace team** (bold means confirmed):
    - **Peter Willendrup, Emmanuel Farhi, Erik Knudsen, Jakob Garde, Tobias Weber, Torben R Nielsen, Mads Bertelsen**
  - **RAMP team from the UK**  
(RAMP is relatively young “McStas equivalent” with GPU-support from the beginning via C++ and OpenCL.)
    - **Gino Cassella, Göran Nilson**
  - **We didn’t attract someone from Nvidia, but we have access to Guido Juckeland in Dresden**
- **Code-camp focal points:**
  - Port as many remaining instruments / components as possible to GPU
  - Experiment with “telescopic flow”/V2/V3, i.e. a different approach to handling ABSORB’s and SPLIT’s
  - Experiment with simulation flow between CPU and GPU (a few things can not be done GPU)
  - Comparisons with RAMP
  - Initiate port of GPU work to McXtrace tree
  - Have fun! :-)



*McStas*

